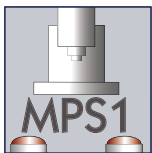
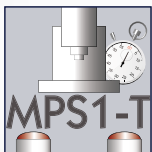


Type MPS-1 controllers are type-tested and approved in accordance with the EC Machinery Directive 2006/42/EC to work with presses in workstations with manual loading and open tools. Here, safety is provided by the controller, which is designed to be both electrically and pneumatically redundant.

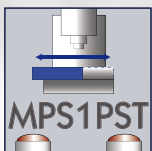
Type MPS-1 controllers comprise an electrical safety module with two-hand buttons and an electronic 5-digit parts counter. It is possible to switch from two-hand mode to an external start signal for the press, e.g. a foot switch, by means of a key-operated switch if a safe tool is used. The foot switch or equivalent is not included with the Type MPS-1 controller.



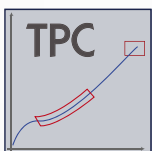
**MPS-1**  
Basic version for two-hand operation.



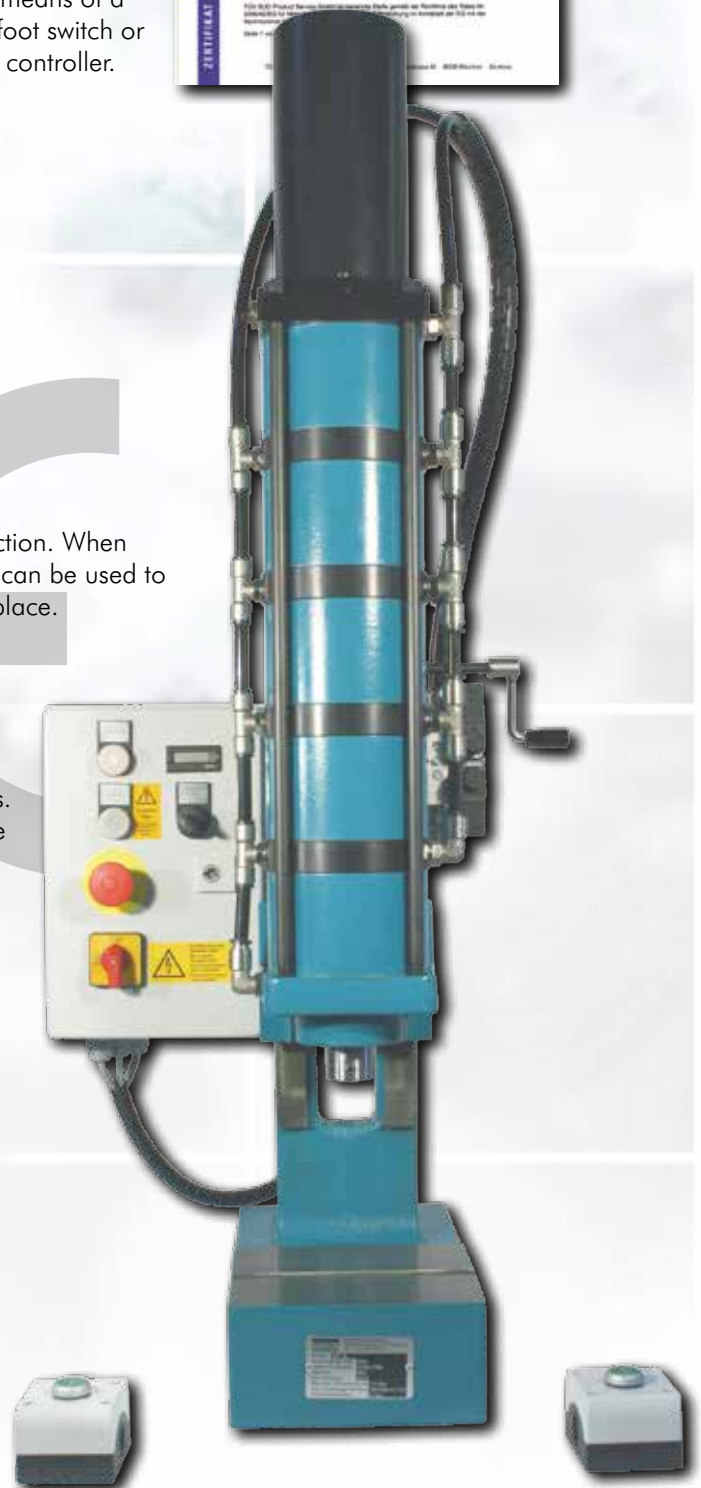
**MPS-1 T**  
MPS-1 controller with additional stop time function. When the press has reached its end position, a timer can be used to determine when the return stroke should take place.



**MPS-1 PST**  
This type of MPS-1 controller is used to control a pneumatic slide table in addition to the press. The scope of supply also includes the stop time function (see MPS-1 T)



**MPS-1 TPC**  
MPS-1 controller with an additional module TPC-MIDI for force/displacement monitoring.



## Applications:

Joining and assembly processes using presses must today be carried out safely and if possible without retrospective checking. Specified parameters which define the press process must be maintained during production. Only in this way can the quality and safety of the manufactured product be guaranteed. For this reason, TPC-MIDI is used wherever consistent joining processes are required, the progress of which has to be checked and if applicable documented by means of software.

TPC-MIDI monitors the press operation, compares the actual progress with the requirements and subsequently evaluates it. In this way, reject parts can be reliably detected and separated out.

TPC-MIDI can be used both with hand-operated presses and with pneumatic presses. In the case of pneumatic presses, the **MPS-1 TPC** controller is supplied together with a PLC onto which the type-tested two-hand MPS-1 safety controller is superimposed.

However, the TPC-MIDI is also available as a pure system component if a PLC environment already exists, e.g. in an automation system.

## The advantages:

- ▶ TPC-MIDI can be programmed via the membrane keyboard or conveniently using the PC software.
- ▶ TPC-MIDI stores 8 different measuring programs
- ▶ 3 windows possible per program
- ▶ Modern curve evaluation via freely parameterisable windows
- ▶ 4 window types: insertion, pass-through and block windows as well as an envelope curve.
- ▶ Force measurement directly in the force characteristic with DMS sensor developed especially for presses.
- ▶ Software for programming and saving measuring programs
- ▶ Documentation of each press operation

## Clear OK / NOK message

With OK parts, the indicator light is green and the press is ready for the next working stroke.

NOK parts are reliably reported by the TPC-MIDI as an audible signal and by a red indicator light.

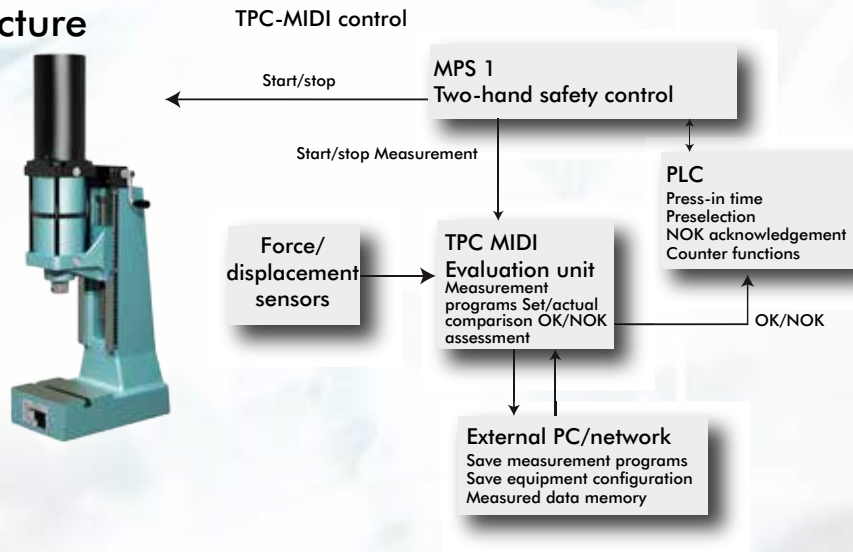
The next press stroke cannot be initiated until the error has been acknowledged.



Laptop not included

DA 850-40-100 with MPS-1 TPC

### System structure



### Load cell force sensors for TPC-MIDI

The load cell force sensor is fixed inside the ram bore. The tool holder can be fixed in the hole at the other end of the sensor. The force sensor is therefore always directly in the force flow between the press ram and the tool.

Measurement range	Measured value divergence	Tool holder
0 – 500 N	≤ ± 0.5% of EV	10H7 x 24 mm
0 – 1 kN	≤ ± 0.5% of EV	10H7 x 24 mm
0 – 2 kN	≤ ± 0.5% of EV	10H7 x 24 mm
0 – 5 kN	≤ ± 2.0% of EV	10H7 x 24 mm
0 – 10 kN	≤ ± 2.0% of EV	10H7 x 24 mm
0 – 20 kN	≤ ± 1.0% of EV	10H7 x 24 mm
0 – 50 kN	≤ ± 1.0% of EV	20H7 x 24 mm
0 – 100 kN	≤ ± 1.0% of EV	20H7 x 24 mm



Unless expressly required to the contrary, the load cell force sensor is selected to match the maximum capacity of the press used

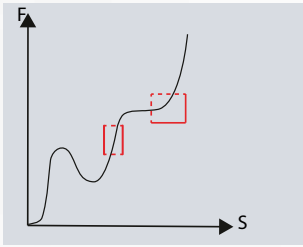
### Potentiometric travel meter

Travel is measured potentiometrically. The service life of the sensors is 10<sup>8</sup> movements

Press stroke	Resolution	Linearity error
40 mm	0.025 mm	0.42%
60/80 mm	0.038 mm	0.41%
100 mm	0.050 mm	0.40%
120 mm	0.075 mm	0.40%

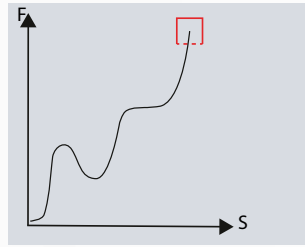
## Monitoring windows

Pass-through window



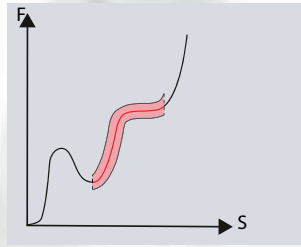
The force/displacement curve must pass through the window from the entry to the exit side as defined without one of the other window boundaries being infringed. The entry and exit sides can be freely selected.

Block window



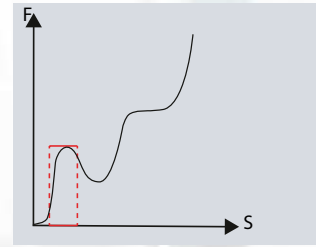
The block window monitors the final values of the press operation. With this type of window, the force/displacement curve must enter the specified entry side and must not leave the window again.

Envelope curve



The measuring curve must pass continuously through the envelope curve and must not infringe it. The envelope curve is taught by means of a teach-in process. Its X-axis parameters and the delta-Y, i.e. the force tolerance range, are then defined.

Monitoring window

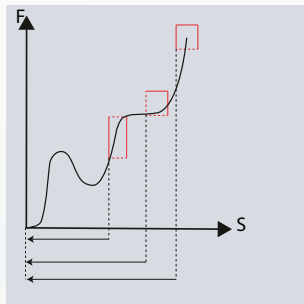


With this window, it is possible to monitor at the start of the press-in process whether parts become jammed or are not correctly inserted. If the force rises too steeply, the window is exited upwards and a real-time signal is generated that can be used to abort the process.

## The reference points of the monitoring windows

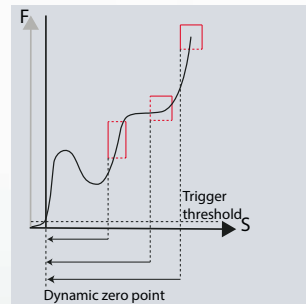
The reference points of the monitoring windows on the X-axis can be defined both rigidly and dynamically.

Absolute



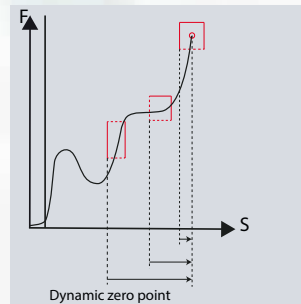
In the case of assembled parts with high repeat accuracy, the calibrated zero point of the displacement sensor on the X-axis is used as the reference point.

Trigger



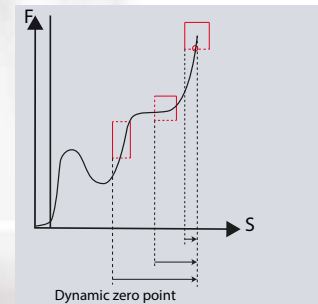
If the assembly sequence is identical as such, but the start of assembly has a major deviation on the X-axis, the beginning of the measurement can be defined by setting a trigger threshold on the Y-axis.

End force



If a measurement with an absolute or a trigger reference point is not useful, the position of the end force (Fmax) on the X-axis can be selected as the reference point. The position of the evaluation window on the X-axis then relates in reverse to this dynamic zero point.

Block window



If the end force shows a wide spread, the reference point of the evaluation windows can also be defined using the entry of the curve into the block window. Any values after the block window has been reached are no longer taken into account. The position of the evaluation windows on the X-axis then relates in reverse to this dynamic zero point.



